

REPUBLIQUE ALGERIENNE DEMOCRATIQUE ET POPULAIRE
Ministère de l'Enseignement Supérieur et de la Recherche Scientifique
Université Mohamed Khider-BISKRA.

Faculté des sciences exactes et des
sciences de la nature et de la vie



Département d'informatique

Machine Learning (ML)

Dr. TBERMACINE Ahmed

CONTENT SUMMARY

Chapter 1 : Introduction to Machine Learning (ML)

Chapter2 : Artificial Neural Network (ANN)

Chapter3: Deep learning (DL)

Chapter 4: Bayesian Network (BN)

Chapter 5: Hidden Markov model (HMM)

Chapter 6: Applications of ML in communication networks

CHAPTER 3: DEEP LEARNING (DL)

3

INTRODUCTION

- In this chapter, we'll dive into the foundations of deep learning, placing a special spotlight on Convolutional Neural Networks (CNNs).
- We 'll get a grasp of what deep learning is all about, especially when it comes to dealing with images.
- By the end of this chapter, you'll be well-versed in how CNNs function and their crucial role in tasks like recognizing objects in pictures.

LEARNING OBJECTIVES

- Gain insights into deep learning, its applications, and the emergence of CNNs.
- Comprehend the architecture and training of CNNs for image-related tasks.

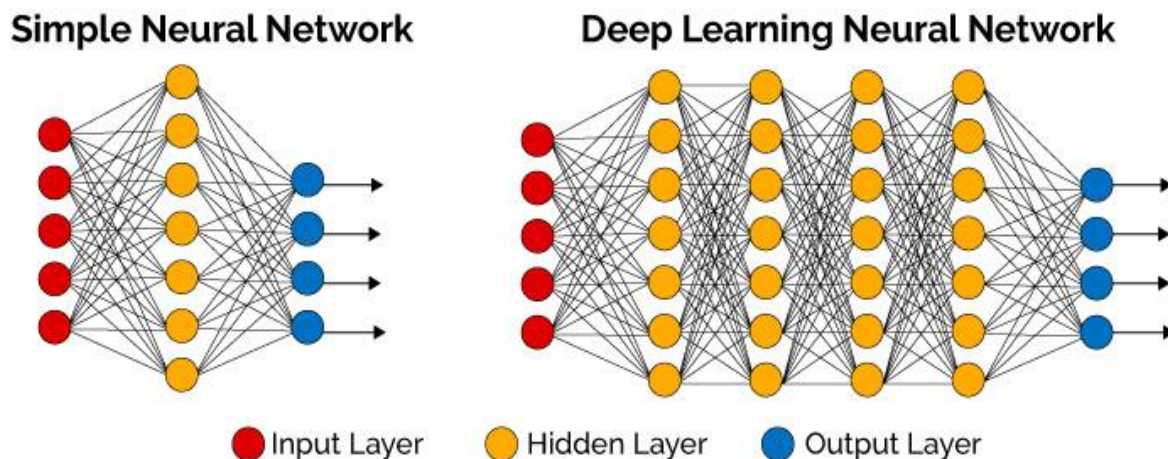
DEEP LEARNING (DL)

- **What is Deep Learning?**
- Deep Learning is a subfield of machine learning and artificial intelligence that revolves around training **artificial neural networks**, particularly deep neural networks, to perform complex tasks.
- These deep neural networks consist of multiple layers, which enable them to capture intricate patterns in data.

DEEP LEARNING (DL)

❖ Deep Neural Networks (DNN)

- Deep neural networks are characterized by having many hidden layers.
- These layers introduce a hierarchical representation of data.
- A deep neural network consists of multiple layers:



- Mathematically, a deep neural network can be represented as a composition of functions:
 - $F(x) = f_n(f_{n-1}(\dots f_2(f_1(x; W_1, b_1); W_2, b_2) \dots; W_{n-1}, b_{n-1}); W_n, b_n)$

DEEP LEARNING (DL)

- **Panorama of Prominent Deep Learning Models**
 - Convolutional Neural Networks (CNNs)
 - Long Short-Term Memory Networks (LSTMs)
 - Autoencoders
 - Generative Adversarial Networks (GANs)
 - Transformers
 - Deep Reinforcement Learning (DRL)
 - Capsule Networks (CapsNets)

DEEP LEARNING (DL)

❖ Differences between DNN and ML

○ Scope:

- **ML:** is a broader field that encompasses various techniques for teaching a computer system to learn from data and make predictions.
It includes both traditional statistical methods and modern techniques like deep learning.
- **DNN:** are a specific subset of machine learning techniques that are based on artificial neural networks with multiple hidden layers.

DEEP LEARNING (DL)

❖ Differences between DNN and ML

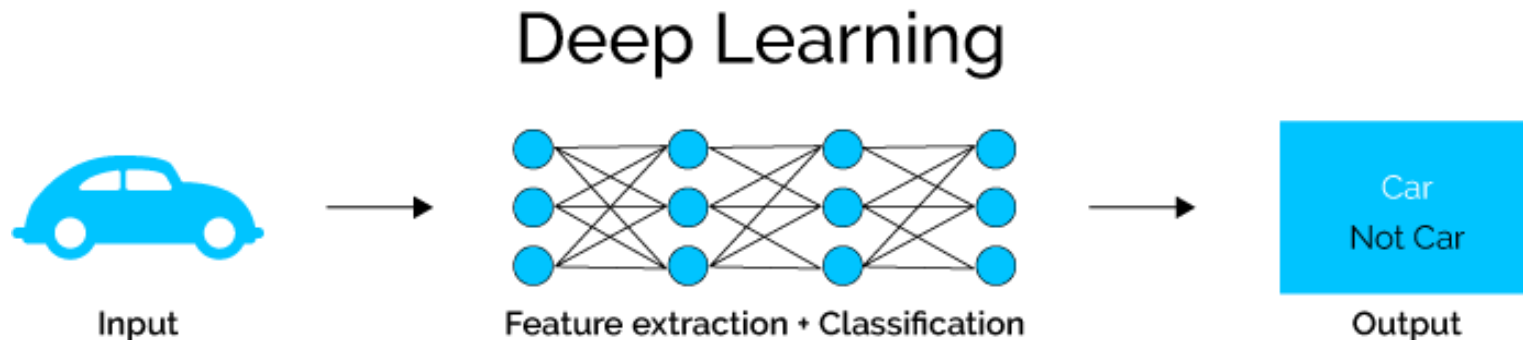
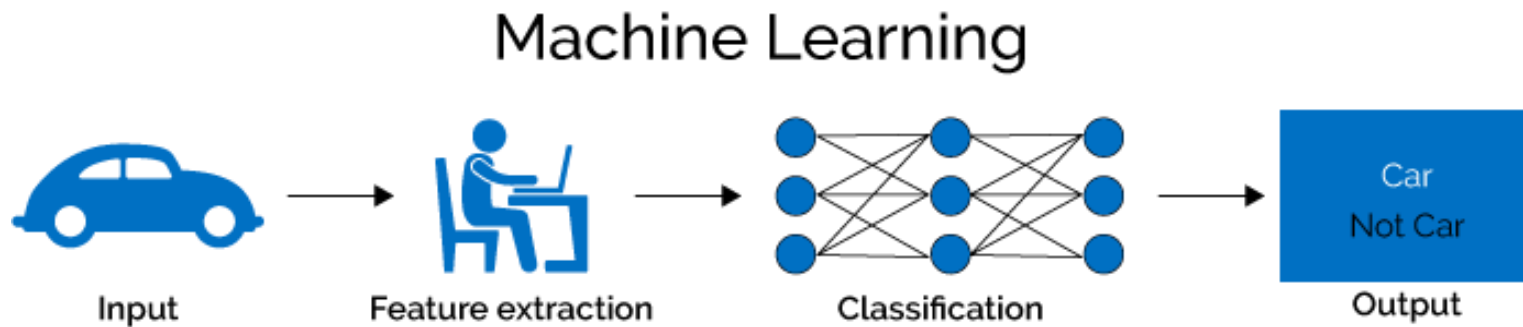
○ Model Complexity:

- **ML:** ML models can be relatively simple.
- **DNN:** DNNs are characterized by their deep architectures, typically consisting of many layers.

DEEP LEARNING (DL)

❖ Differences between DNN and ML

○ Feature Engineering:



DEEP LEARNING (DL)

❖ Differences between DNN and ML

○ Data Requirements:

- **ML:** ML models can work with smaller datasets effectively, as they often rely on hand-crafted features.
- **DNN:** DNNs tend to require larger datasets for training, as they need substantial amounts of data to learn complex patterns.

DEEP LEARNING (DL)

❖ Differences between DNN and ML

○ Training Process:

- **ML:** Training ML models is often quicker and less computationally intensive compared to training deep neural networks.
- **DNNs:** Training DNNs can be computationally expensive and time-consuming, often requiring specialized hardware like GPUs or TPUs.

DEEP LEARNING (DL)

❖ Differences between DNN and ML

○ Interpretability:

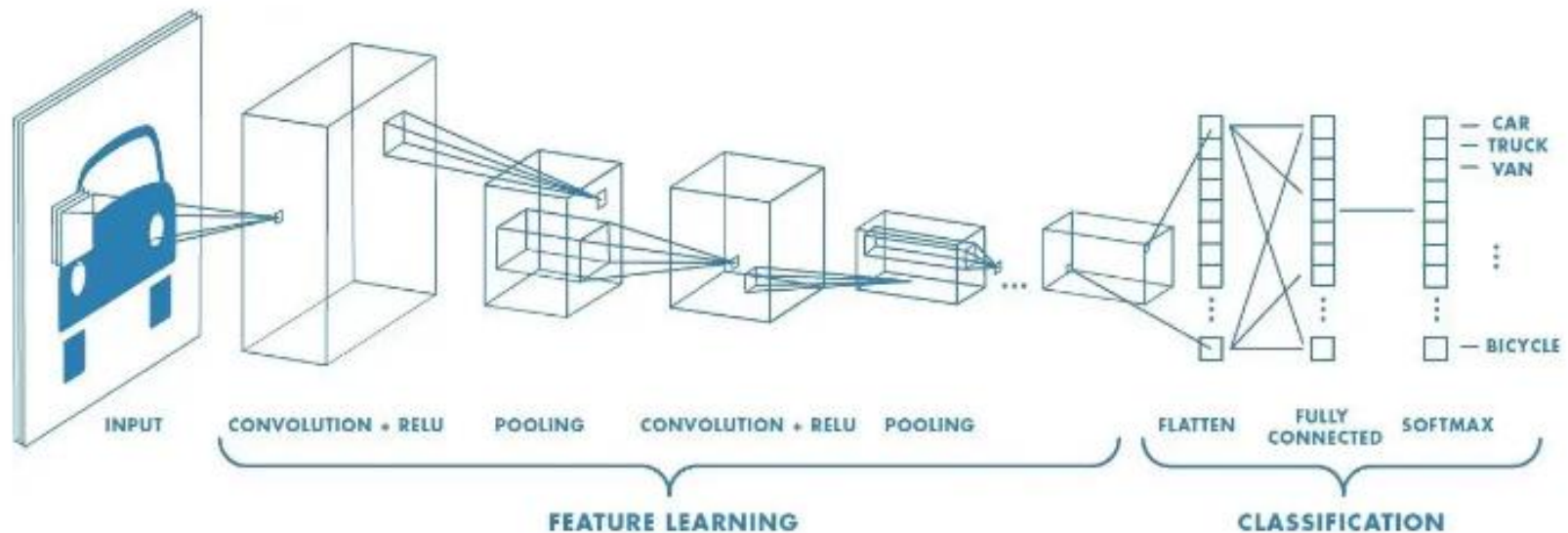
- **ML:** ML models are relatively interpretable, meaning it's easier to understand the factors influencing their predictions.
- **DNNs:** are often considered as "black boxes" because their inner workings can be challenging to interpret.

CONVOLUTIONAL NEURAL NETWORKS

(CNN/ConvNet)

CONVOLUTIONAL NEURAL NETWORKS (CNN)

- CNN is a class of [deep neural networks](#), most commonly applied to analyze visual imagery.



CONVOLUTIONAL LAYER

Convolutional Layer

- The convolution layer is the core building block of CNN.
- The main objective of convolution is to extract features such as edges, colors, corners from the input.
- As we go deeper inside the network, the network starts identifying more complex features such as shapes, digits, face parts as well.

$$O_h = \frac{I_h - k_h + 2P}{S_h} + 1$$

$$O_w = \frac{I_w - k_w + 2P}{S_w} + 1$$

1 _{x1}	1 _{x0}	1 _{x1}	0	0
0 _{x0}	1 _{x1}	1 _{x0}	1	0
0 _{x1}	0 _{x0}	1 _{x1}	1	1
0	0	1	1	0
0	1	1	0	0

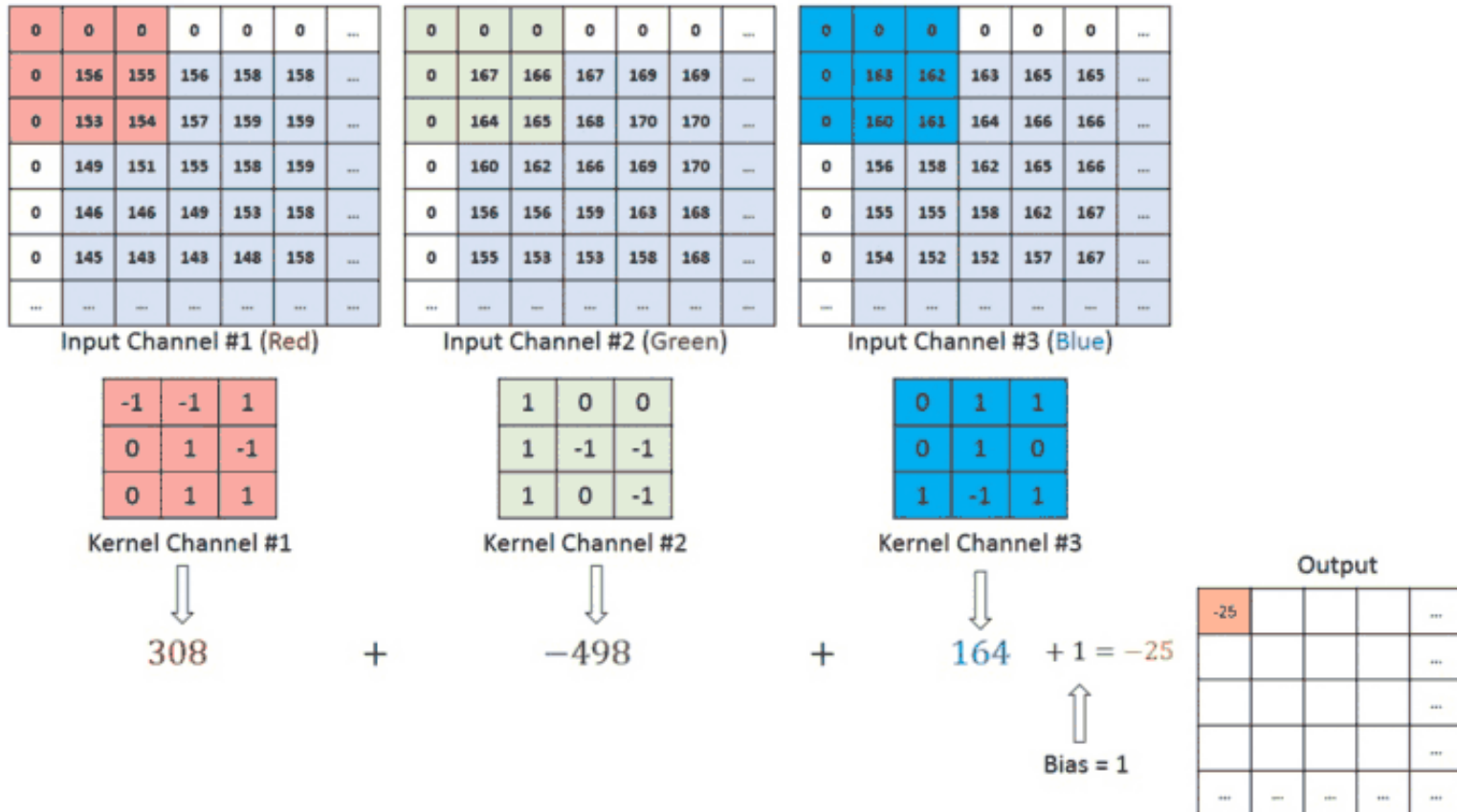
Image

4		

Convolved Feature

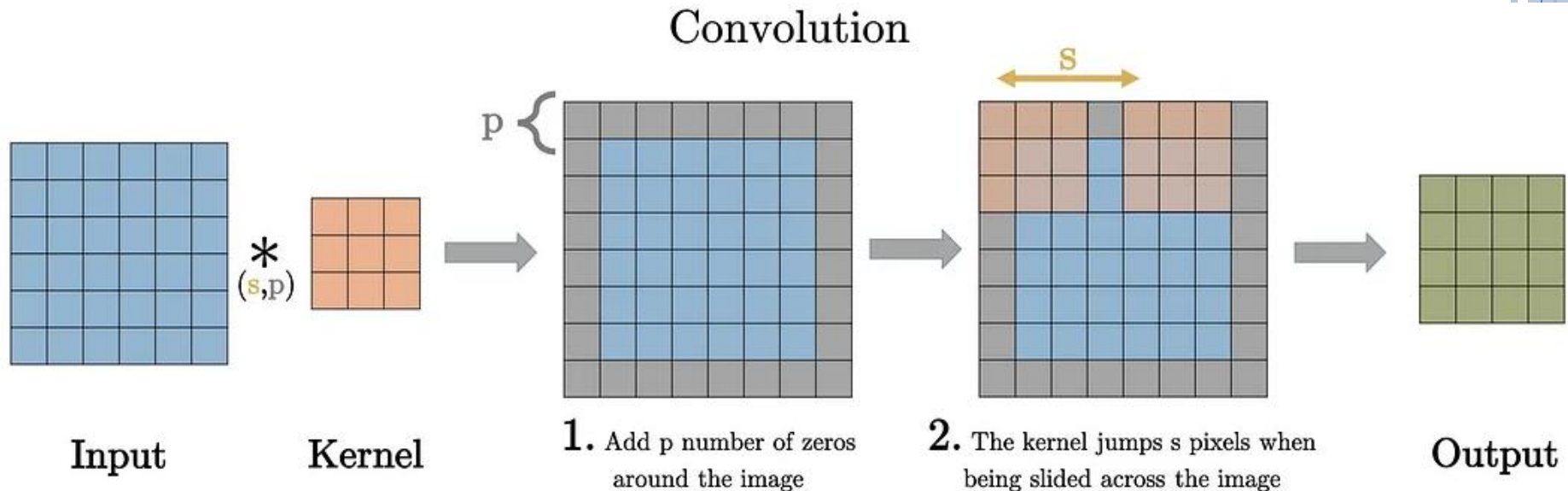
CONVOLUTIONAL LAYER

- If the image is RGB



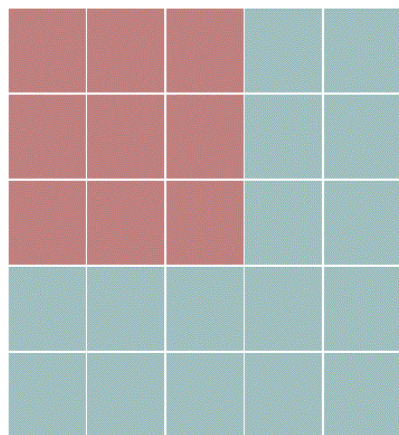
CONVOLUTIONAL LAYER

- **Kernel Size:** defines the field of view of the convolution
- **Padding (p):** defines how the border of a sample is handled.
- **Stride:** defines the step size of the kernel when traversing the input image.

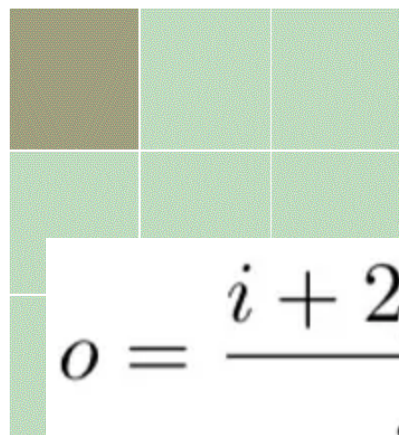


CONVOLUTIONAL LAYER

Type: conv - Stride: 1 Padding: 0

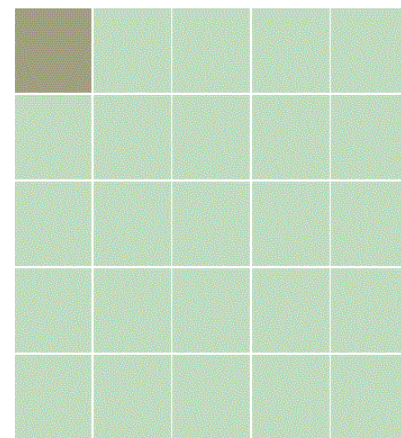
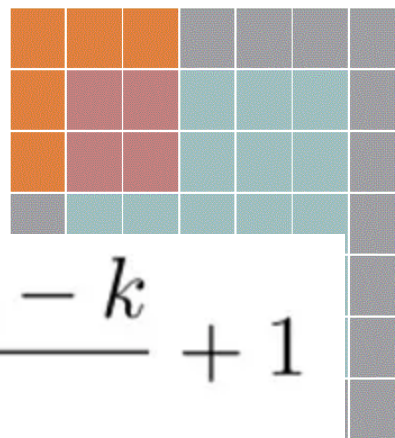


Input



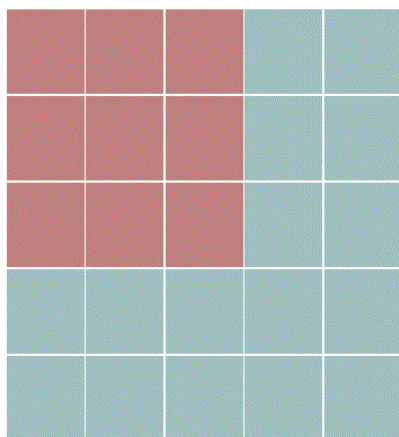
$$o = \frac{i + 2p - k}{s} + 1$$

Type: conv - Stride: 1 Padding: 1

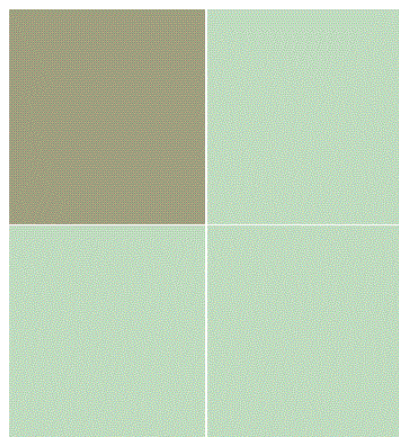


Output

Type: conv - Stride: 2 Padding: 0

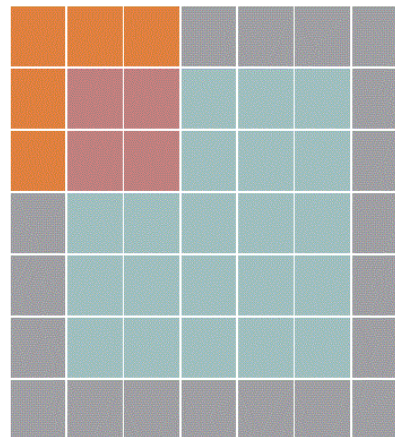


Input

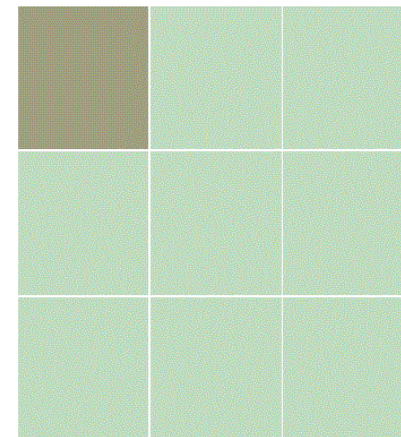


Output

Type: conv - Stride: 2 Padding: 1



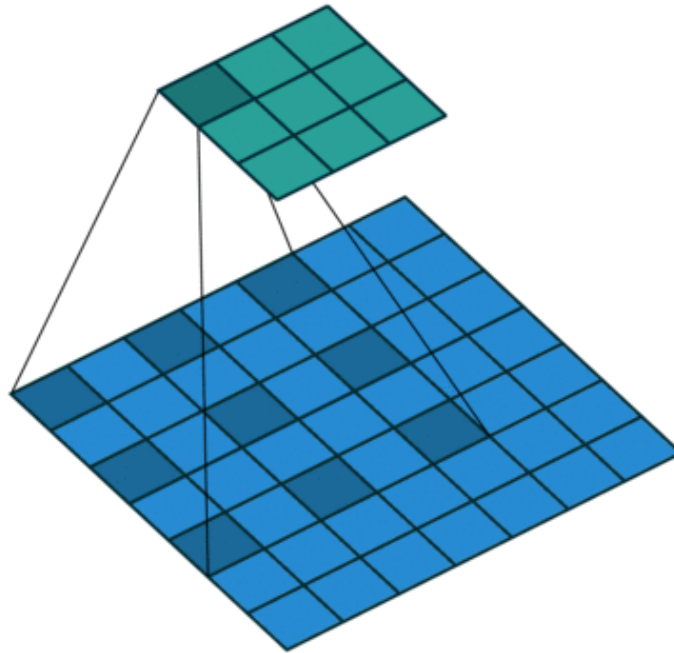
Input



Output

CONVOLUTIONAL LAYER

- ❖ Different Types of Convolutions in Deep Learning
 - Dilated Convolutions (atrous convolutions)



2D convolution using

2 and no padding

CONVOLUTIONAL LAYER

- ❖ Different Types of Convolutions in Deep Learning
 - Transposed Convolutions: it's not a deconvolution

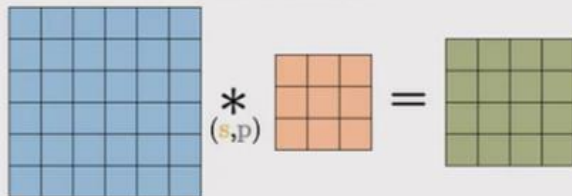
This is deconvolution:



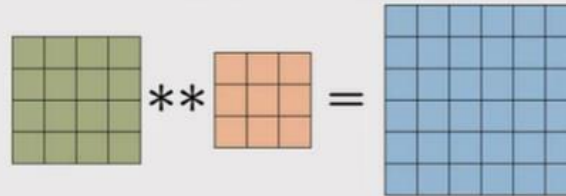
CONVOLUTIONAL LAYER

- ❖ **Different Types of Convolutions in Deep Learning**
- ❖ **Transposed Convolutions (TC)**
 - TC layer resembles the Deconvolutional layer as they both produce the same spatial dimension.
 - It is carried out for **Upsampling**.
 - it is defined by the **padding** and **stride**.

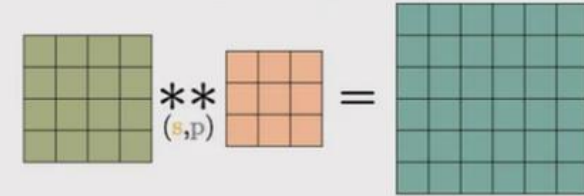
Convolution



DeConvolution

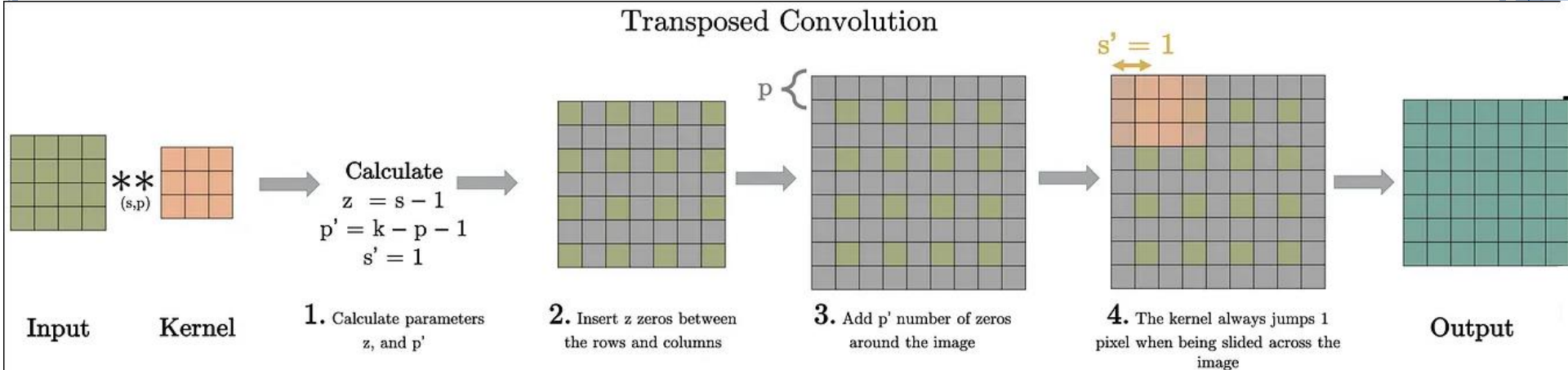


Transposed Convolution



CONVOLUTIONAL LAYER

- ❖ **Different Types of Convolutions in Deep Learning**
 - Implementing a **Transposed Convolutions** layer can be better explained as a 4 step process:

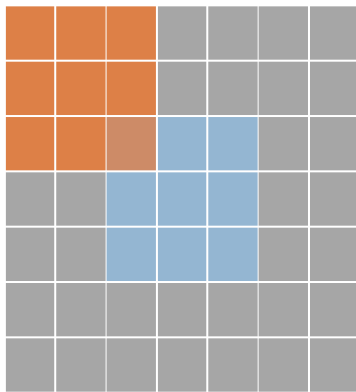


CONVOLUTIONAL LAYER

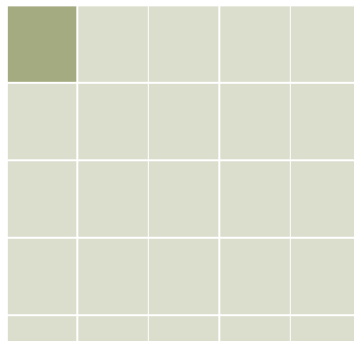
❖ Different Types of Convolutions in Deep Learning

○ Transposed Convolutions

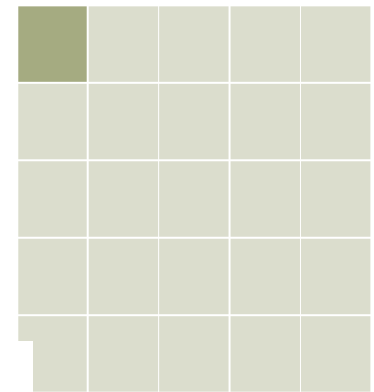
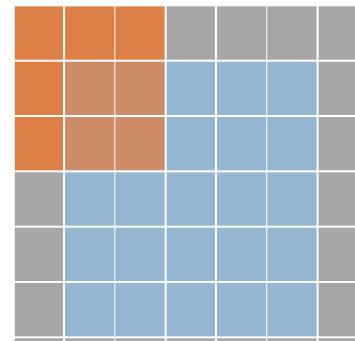
Type: transposed conv - Stride: 1 Padding: 0



Input



Type: transposed conv - Stride: 1 Padding: 1

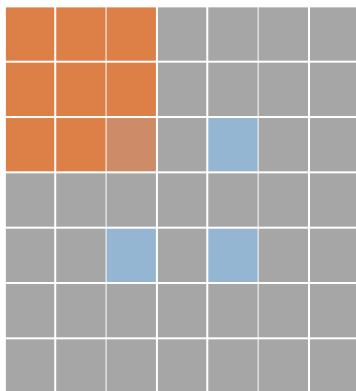


Output

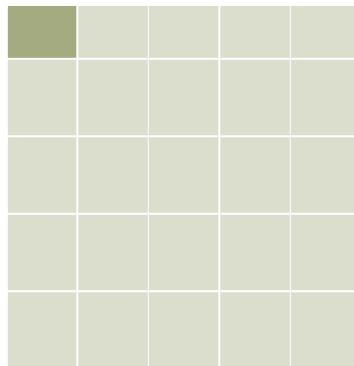
Type: transposed conv

$$o = (i - 1) \times s + k - 2p$$

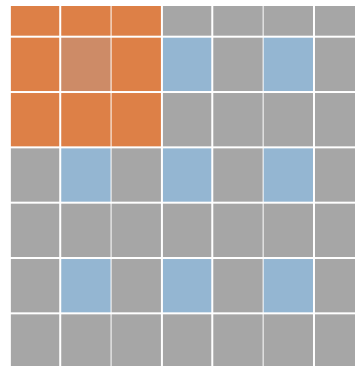
Stride: 2 Padding: 1



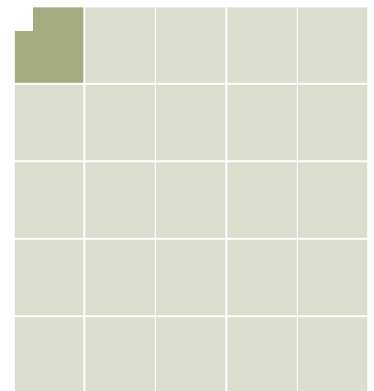
Input



Output



Input



Output

CONVOLUTIONAL NEURAL NETWORKS

- ❖ Different Types of Convolutions in Deep Learning
 - Transposed Convolutions “Summary”

Comparison					
Conv Type	Operation	Zero Insertions	Padding	Stride	Output Size
Standard	Downsampling	0	p	s	$(i+2p-k)/s + 1$
Transposed	Upsampling	$(s - 1)$	$(k-p-1)$	1	$(i-1)*s+k-2p$

- The idea behind transposed convolution is to carry out trainable upsampling
- Transposed convolutions are standard convolutions but with a modified input feature map.
- The stride and padding **do not** correspond to the number of zeros added around the image and the amount of shift in the kernel when sliding it across the input, as they would in a standard convolution operation.

CONVOLUTIONAL LAYER

❖ Different Types of Convolutions in Deep Learning

○ Separable Convolutions

- we split the kernel operation into multiple steps
- convolution $\rightarrow y = \text{conv}(x, k)$
- where y is the output image, x is the input image, and k is the kernel.
- let's assume k can be calculated by: $k = k1.\text{dot}(k2)$.
- This would make it a separable convolution because instead of doing a 2D convolution with k , we could get to the same result by doing 2 1D convolutions with $k1$ and $k2$.

CONVOLUTIONAL LAYER

❖ Different Types of Convolutions in Deep Learning

○ Separable Convolutions: Example: Sobel kernel

-1	0	+1
-2	0	+2
-1	0	+1

x filter

+1	+2	+1
0	0	0
-1	-2	-1

y filter

Sobel X and Y filters

- You could get the same kernel by multiplying the vector $[1, 0, -1]$ and $[1, 2, 1]$. T.
- 6 instead of 9 parameters while doing the same operation.
- This example shows what's called a **spatial separable convolution**.

POOLING LAYER

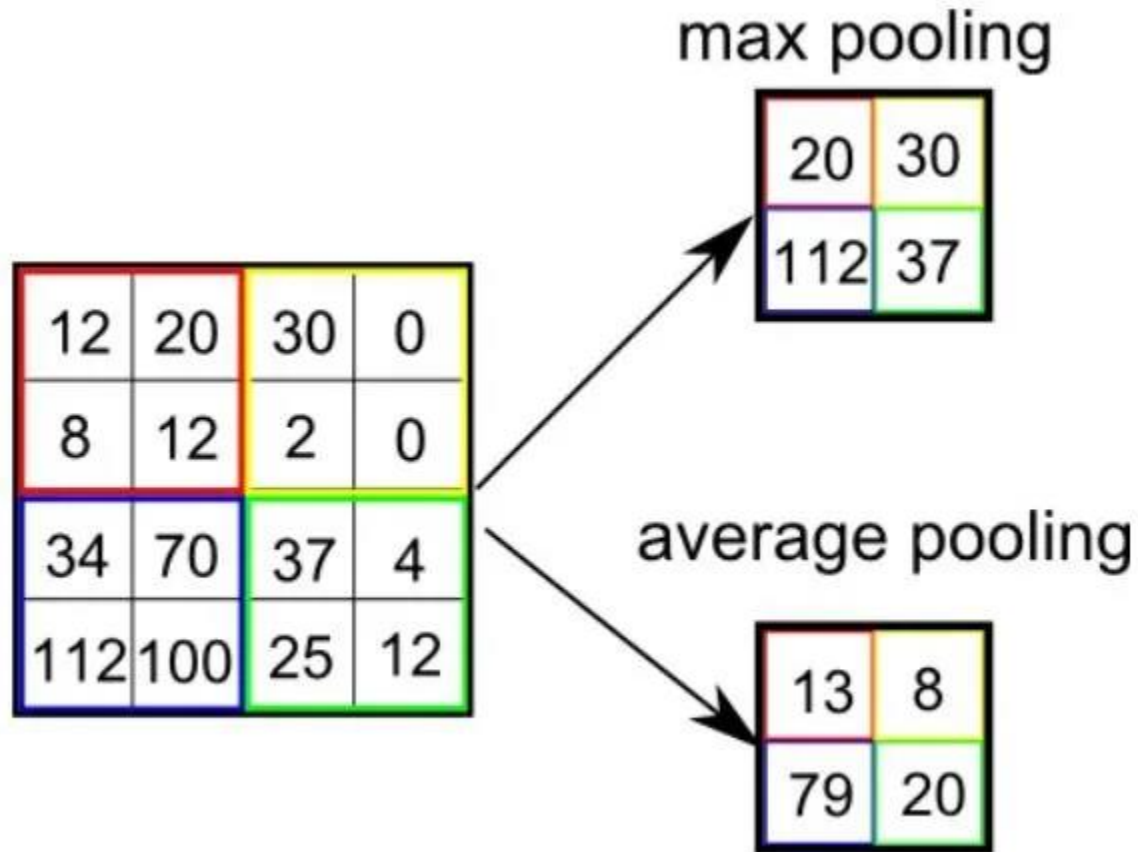
- **Pooling layer = Sub-sampling Layer**
- This layer decrease the computational power required to process the data.
- It is done by decreasing the dimensions of the featured matrix even more.
- It extract the dominant features from a restricted amount of neighborhood.

3.0	3.0	3.0
3.0	3.0	3.0
3.0	2.0	3.0

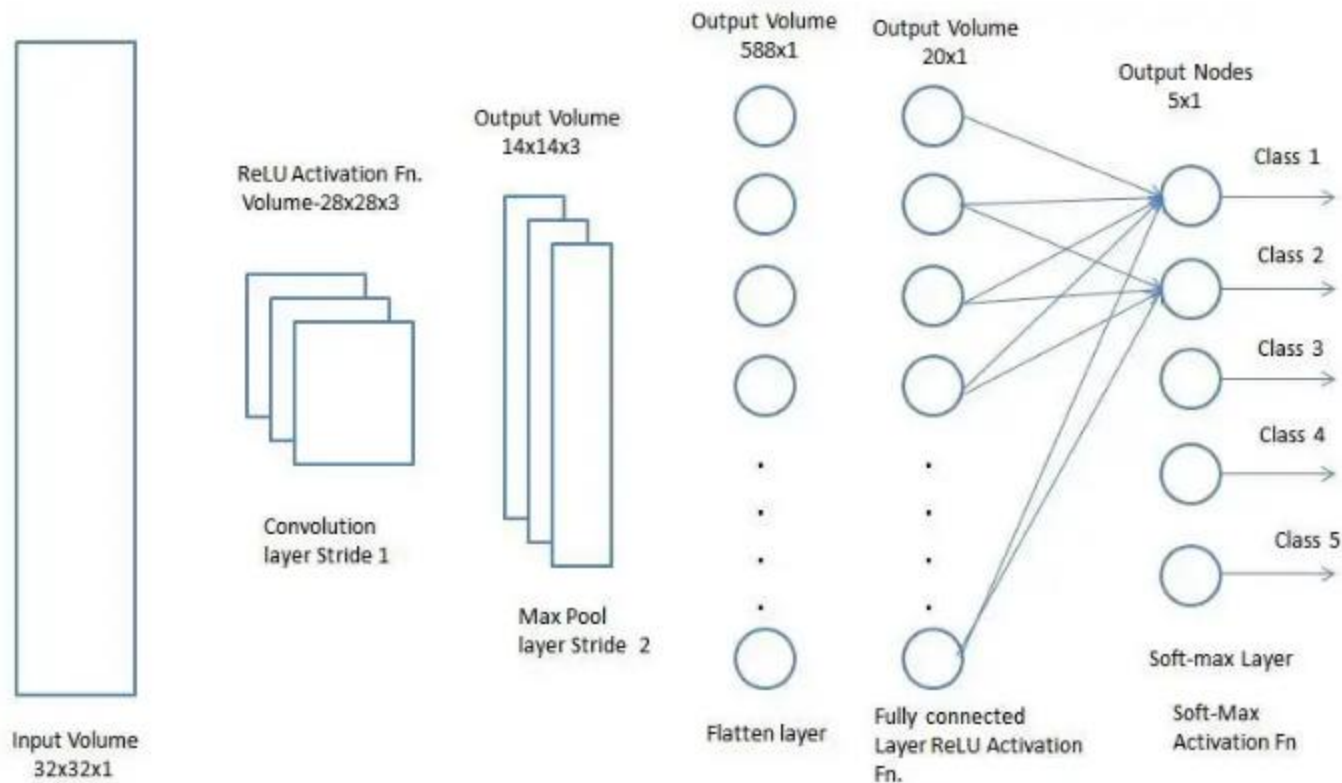
3	3	2	1	0
0	0	1	3	1
3	1	2	2	3
2	0	0	2	2
2	0	0	0	1

POOLING LAYER

- Pooling Layer types:

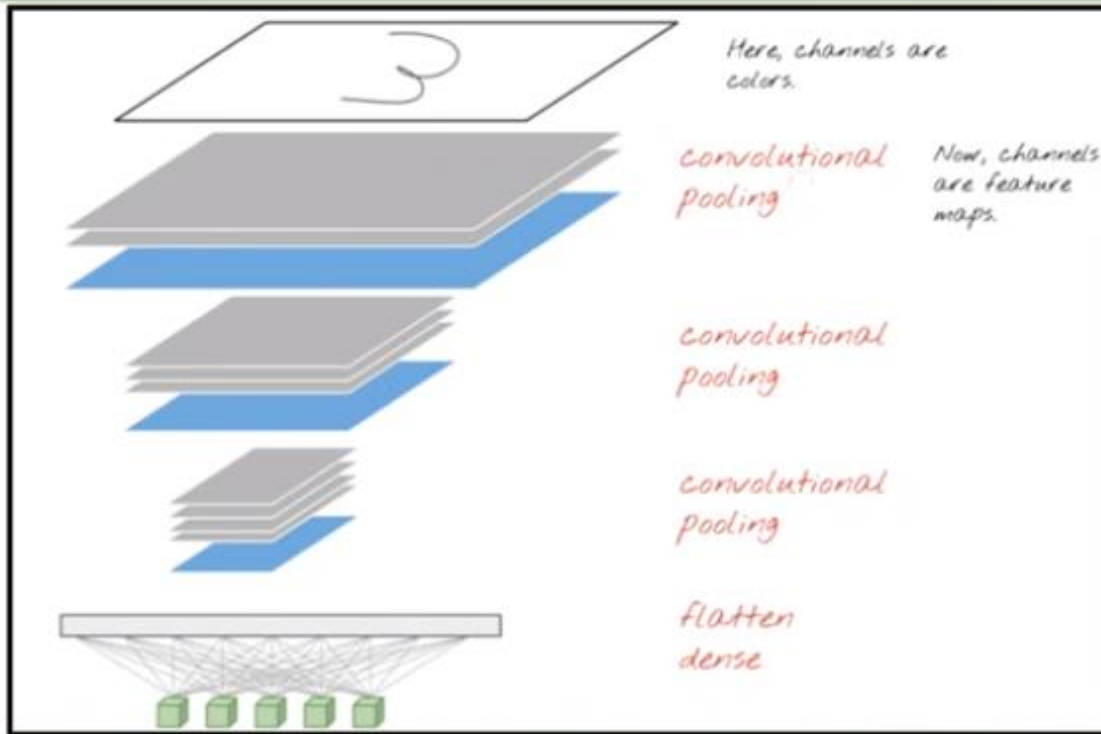


FULLY CONNECTED LAYER (FCL)



CONVOLUTIONAL NEURAL NETWORKS

Common Set-up



In order to implement CNNs, most successful architecture uses one or more stacks of convolution + pool layers with relu activation, followed by a flatten layer then one or two dense layers.

CONVOLUTIONAL NEURAL NETWORKS

○ Various architectures of CNNs

- LeNet
- AlexNet
- VGGNet
- GoogLeNet
- ResNet
- ZFNet

CONVOLUTIONAL NEURAL NETWORKS

❖ Summary

- Provide input image into convolution layer
- Choose parameters, apply filters with strides, padding if requires. Perform convolution on the image and apply ReLU activation to the matrix.
- Perform pooling to reduce dimensionality size
- Add as many convolutional layers until satisfied
- Flatten the output and feed into a FC Layer
- Output the class using an activation function (Logistic Regression with cost functions) and classifies images.

CONVOLUTIONAL NEURAL NETWORKS

CNN project 1: Cat Dog Recognition

```
1# Importing the Keras libraries and packages
2from keras.models import Sequential
3from keras.layers import Conv2D
4from keras.layers import MaxPooling2D
5from keras.layers import Flatten
6from keras.layers import Dense
7# Initialising the CNN
8classifier = Sequential()
9# Step 1 - Convolution
10classifier.add(Conv2D(32, (3, 3), input_shape = (64, 64, 3),
11                    activation = 'relu'))
12# Step 2 - Pooling
13classifier.add(MaxPooling2D(pool_size = (2, 2)))
14# Adding a second convolutional layer
15classifier.add(Conv2D(32, (3, 3), activation = 'relu'))
16classifier.add(MaxPooling2D(pool_size = (2, 2)))
17# Step 3 - Flattening
18classifier.add(Flatten())
19# Step 4 - Full connection
20classifier.add(Dense(units = 128, activation = 'relu'))
21classifier.add(Dense(units = 1, activation = 'sigmoid'))
22# Compiling the CNN
23classifier.compile(optimizer = 'adam', loss = 'binary_crossentropy',
24                 metrics = ['accuracy'])
25# Part 2 - Fitting the CNN to the images
26from keras.preprocessing.image import ImageDataGenerator
27train_datagen = ImageDataGenerator(rescale = 1./255,
28                                   shear_range = 0.2,
29                                   zoom_range = 0.2,
30                                   horizontal_flip = True)
31test_datagen = ImageDataGenerator(rescale = 1./255)
32training_set = train_datagen.flow_from_directory('dataset/training_set',
33                                                target_size = (64, 64),
34                                                batch_size = 32,
35                                                class_mode = 'binary')
36test_set = test_datagen.flow_from_directory('dataset/test_set',
37                                           target_size = (64, 64),
38                                           batch_size = 32,
39                                           class_mode = 'binary')
40classifier.fit_generator(training_set,
41                        steps_per_epoch = 8000,
42                        epochs = 25,
43                        validation_data = test_set,
44                        validation_steps = 2000)
45# Part 3 - Making new predictions
46import numpy as np
47from keras.preprocessing import image
48test_image = image.load_img('dataset/single_prediction/cat_or_dog_1.jpg',
49                            target_size = (64, 64))
50test_image = image.img_to_array(test_image)
51test_image = np.expand_dims(test_image, axis = 0)
52result = classifier.predict(test_image)
53training_set.class_indices
54if result[0][0] == 1:
55    prediction = 'dog'
56else:
57    prediction = 'cat'
58print(prediction)
```

Filters 32

Filter's shape

64x64 resolution and "3" stands for RGB

2x2 matrix

number of nodes

By : Hussam Hourani

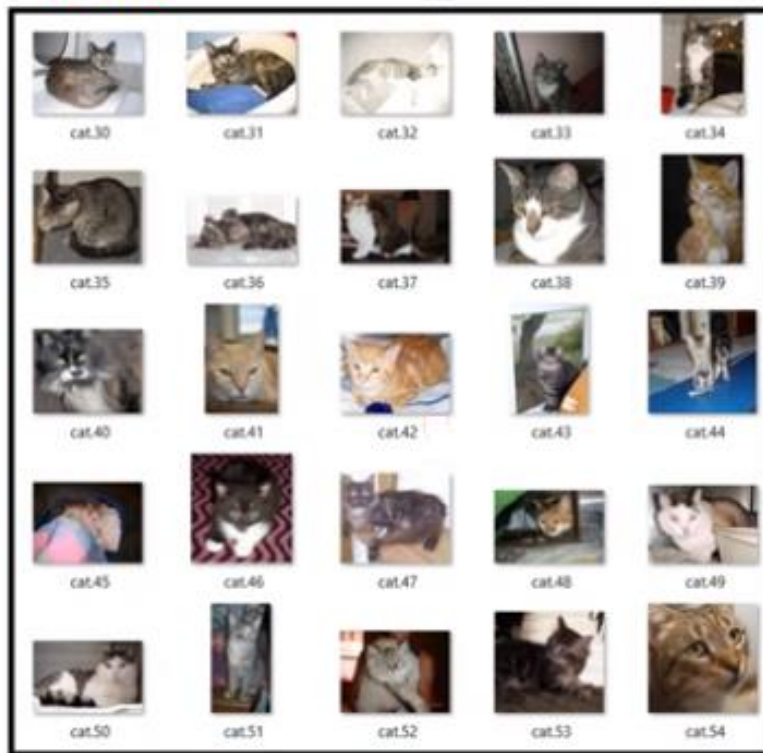
<https://becominghuman.ai/building-an-image-classifier-using-deep-learning-in-python-totally-from-a-beginners-perspective-be8dbaf22dd8>

https://github.com/venkateshtata/cnn_medium.

CONVOLUTIONAL NEURAL NETWORKS

CNN project 1: Cat Dog Recognition

Cats dataset\training_set\cats



Dogs dataset\training_set\dogs



CONVOLUTIONAL NEURAL NETWORKS

CNN project 1: Cat Dog Recognition

```
In [1]: runfile('C:/Python36/Mystuff/Keras20_Conv.py', wdir='C:/Python36/Mystuff')
```

```
Using TensorFlow backend.
```

```
Found 2004 images belonging to 2 classes.
```

```
Found 198 images belonging to 2 classes.
```

\dataset\single_prediction



```
Epoch 1/10
```

```
100/100 [=====] - 194s 2s/step - loss: 0.6941 - acc: 0.5435 - val_loss: 0.6661 - val_acc: 0.6464
```

```
Epoch 2/10
```

```
100/100 [=====] - 193s 2s/step - loss: 0.6532 - acc: 0.6213 - val_loss: 0.6158 - val_acc: 0.6767
```

```
Epoch 3/10
```

```
100/100 [=====] - 191s 2s/step - loss: 0.6141 - acc: 0.6661 - val_loss: 0.5784 - val_acc: 0.7121
```

```
Epoch 4/10
```

```
100/100 [=====] - 208s 2s/step - loss: 0.5658 - acc: 0.7094 - val_loss: 0.5674 - val_acc: 0.7323
```

```
Epoch 5/10
```

```
100/100 [=====] - 188s 2s/step - loss: 0.5399 - acc: 0.7338 - val_loss: 0.5832 - val_acc: 0.7020
```

```
Epoch 6/10
```

```
100/100 [=====] - 188s 2s/step - loss: 0.5215 - acc: 0.7348 - val_loss: 0.5224 - val_acc: 0.7474
```

```
Epoch 7/10
```

```
100/100 [=====] - 186s 2s/step - loss: 0.4993 - acc: 0.7541 - val_loss: 0.5278 - val_acc: 0.7475
```

```
Epoch 8/10
```

```
100/100 [=====] - 214s 2s/step - loss: 0.4792 - acc: 0.7757 - val_loss: 0.5346 - val_acc: 0.7575
```

```
Epoch 9/10
```

```
100/100 [=====] - 212s 2s/step - loss: 0.4584 - acc: 0.7900 - val_loss: 0.5620 - val_acc: 0.7272
```

```
Epoch 10/10
```

```
100/100 [=====] - 221s 2s/step - loss: 0.4379 - acc: 0.8060 - val_loss: 0.5833 - val_acc: 0.7122
```

```
dog
```


CONVOLUTIONAL NEURAL NETWORKS

CNN project 2: Text Classification

```
1#https://realpython.com/python-keras-text-classification/
2from keras.models import Sequential
3from keras import layers
4from keras.preprocessing.sequence import pad_sequences
5from keras.preprocessing.text import Tokenizer
6import pandas as pd
7from sklearn.model_selection import train_test_split
8
9filepath_dict = {'yelp': 'yelp_labelled.txt',
10                  'amazon': 'amazon_cells_labelled.txt',
11                  'imdb': 'imdb_labelled.txt'}
12
13df_list = []
14for source, filepath in filepath_dict.items():
15    df = pd.read_csv(filepath, names=['sentence', 'label'], sep='\t')
16    df['source'] = source # Add another column filled with the source
17    df_list.append(df)
18
19df = pd.concat(df_list)
20
21df_yelp = df[df['source'] == 'yelp']
22
23sentences = df_yelp['sentence'].values
24y = df_yelp['label'].values
25
26sentences_train, sentences_test, y_train, y_test = train_test_split(
27    sentences, y, test_size=0.25, random_state=1000)
28
29tokenizer = Tokenizer(num_words=5000)
30tokenizer.fit_on_texts(sentences_train)
31
32X_train = tokenizer.texts_to_sequences(sentences_train)
33X_test = tokenizer.texts_to_sequences(sentences_test)
```

```
35vocab_size = len(tokenizer.word_index) + 1 # Adding 1 because of reserved 0
36
37embedding_dim = 100
38maxlen = 100
39
40X_train = pad_sequences(X_train, padding='post', maxlen=maxlen)
41X_test = pad_sequences(X_test, padding='post', maxlen=maxlen)
42
43model = Sequential()
44model.add(layers.Embedding(vocab_size, embedding_dim, input_length=maxlen))
45model.add(layers.Conv1D(128, 5, activation='relu'))
46model.add(layers.GlobalMaxPooling1D())
47model.add(layers.Dense(10, activation='relu'))
48model.add(layers.Dense(1, activation='sigmoid'))
49model.compile(optimizer='adam',
50              loss='binary_crossentropy',
51              metrics=['accuracy'])
52model.summary()
53
54history = model.fit(X_train, y_train,
55                    epochs=10,
56                    verbose=False,
57                    validation_data=(X_test, y_test),
58                    batch_size=10)
59loss, accuracy = model.evaluate(X_train, y_train, verbose=False)
60print("Training Accuracy: {:.4f}".format(accuracy))
61loss, accuracy = model.evaluate(X_test, y_test, verbose=False)
62print("Testing Accuracy: {:.4f}".format(accuracy))
```

<https://archive.ics.uci.edu/ml/datasets/Sentiment+Labelled+Sentences>

<https://realpython.com/python-keras-text-classification/>

No. 27

CONVOLUTIONAL NEURAL NETWORKS

CNN project 2: Text Classification

text files

	sentence	label	source
0	Wow... Loved this place.	1	yelp
1	Crust is not good.	0	yelp
2	Not tasty and the texture was just nasty.	0	yelp
3	Stopped by during the late May bank holiday of...	1	yelp
4	The selection on the menu was great and so wer...	1	yelp
5	Now I am getting angry and I want my damn pho.	0	yelp
6	Honeslty it didn't taste THAT fresh.)	0	yelp
7	The potatoes were like rubber and you could te...	0	yelp
8	The fries were great too.	1	yelp
9	A great touch.	1	yelp
10	Service was very prompt.	1	yelp
11	Would not go back.	0	yelp
12	The cashier had no care what so ever on what I...	0	yelp
13	I tried the Cape Cod ravioli, chicken,with cran...	1	yelp
14	I was disgusted because I was pretty sure that...	0	yelp
15	I was shocked because no signs indicate cash o...	0	yelp
16	Highly recommended.	1	yelp
17	Waitress was a little slow in service.	0	yelp
18	This place is not worth your time, let alone V...	0	yelp
19	did not like at all.	0	yelp
20	The Burrittos Blah!	0	yelp
21	The food, amazing.	1	yelp
22	Service is also cute.	1	yelp
23	I could care less... The interior is just beau...	1	yelp
24	So they performed.	1	yelp

Name: 0, dtype: object

Layer (type)	Output Shape	Param #
=====		
embedding_1 (Embedding)	(None, 100, 100)	174700

conv1d_1 (Conv1D)	(None, 96, 128)	64128

global_max_pooling1d_1 (Glob	(None, 128)	0

dense_3 (Dense)	(None, 10)	1290

dense_4 (Dense)	(None, 1)	11
=====		

Total params: 240,129

Trainable params: 240,129

Non-trainable params: 0

WARNING:tensorflow:From C:\Anaconda37\lib\site-packages\tensorflow\python\ops\math_grad.py:102: div (from tensorflow.python.ops.math_ops) is deprecated and will be removed in a future version.

Instructions for updating:

Deprecated in favor of operator or tf.math.divide.

Training Accuracy: 1.0000

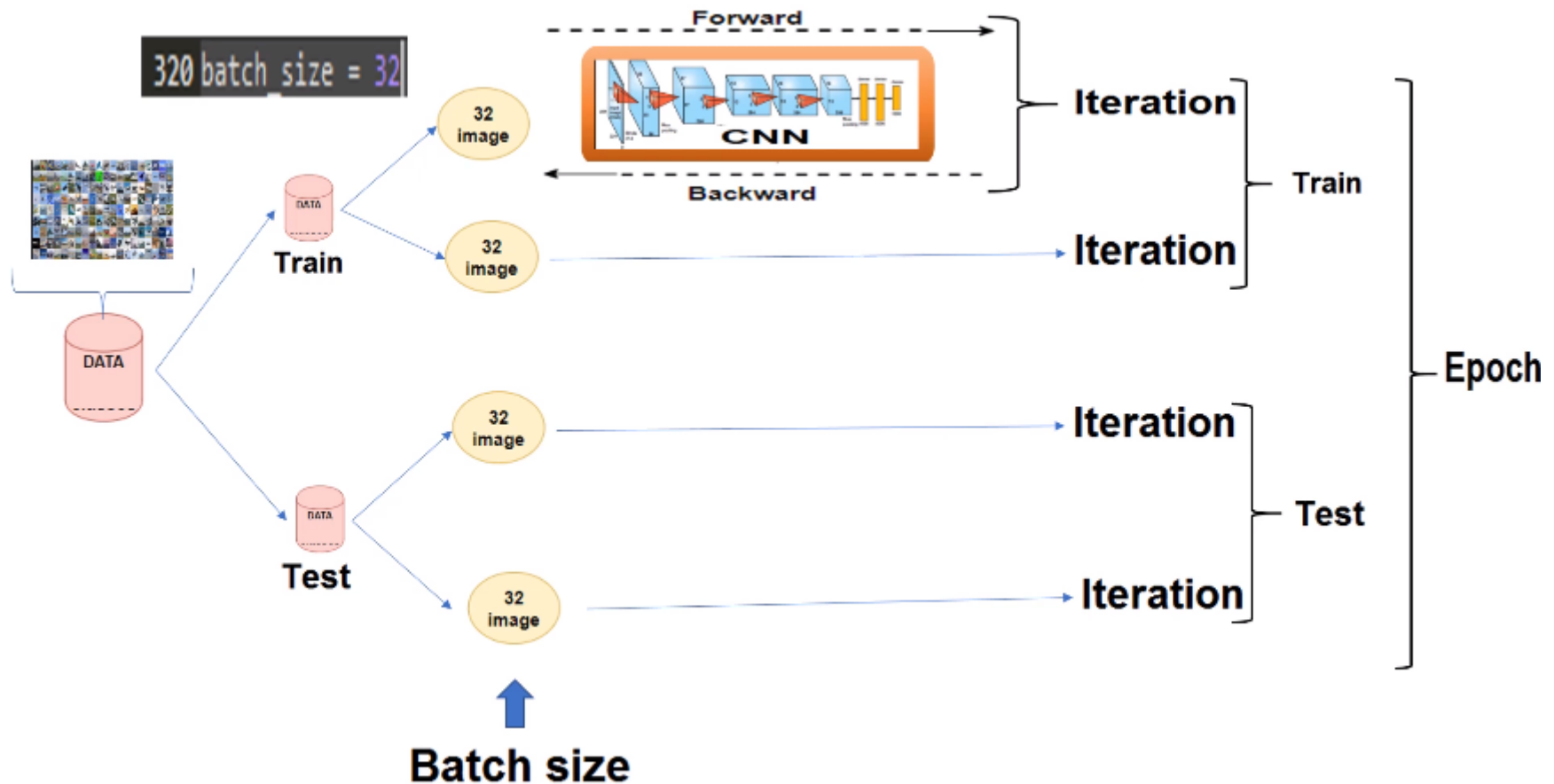
Testing Accuracy: 0.7840

CONVOLUTIONAL NEURAL NETWORKS

❖ Key Differences between MLP and CNN

- CNN is mostly used for Image Data, whereas it is better to use MLP on structural data;
- CNN has less parameters and tries to reduce the dimensions of image whereas in case of MLP number of parameters depends on the data;
- CNN is complex in nature whereas MLP is relatively simple compared to CNN;
- CNN uses special Convolution and Pooling Layers whereas MLP is just a network of Neurons;
- CNN is generally used for huge data as compared to MLP

DL: KEY CONCEPTS



DL: KEY CONCEPTS

❖ Worked Example

- Assume you have a dataset with 200 samples and you choose a batch size of 5 and 1,000 epochs.
- This means that the dataset will be divided into 40 batches, each with 5 samples. The model weights will be updated after each batch of 5 samples.
- This also means that one epoch will involve 40 batches or 40 updates to the model.
- With 1,000 epochs, the model will be exposed to or pass through the whole dataset 1,000 times. That is a total of 40,000 batches during the entire training process.

DL: KEY CONCEPTS

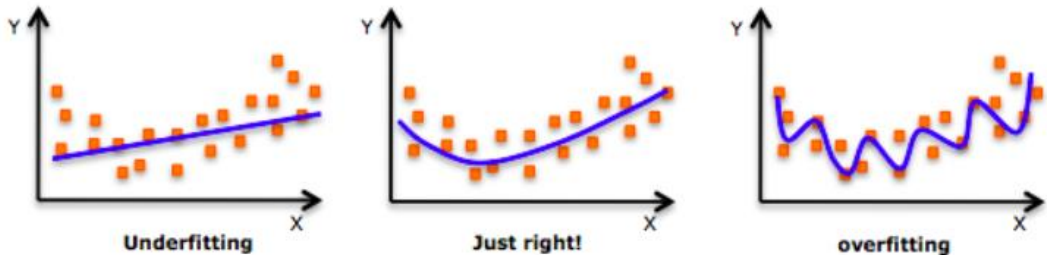
❖ What is Softmax in deep learning?

- Softmax assigns decimal probabilities to each class in a multi-class problem.
- Those decimal probabilities must add up to 1.0.

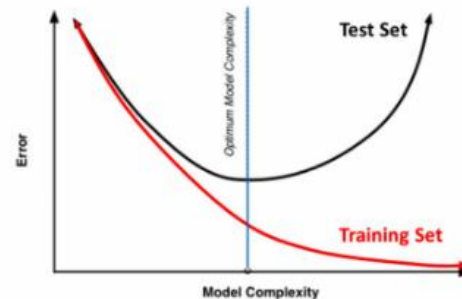
DL: KEY TECHNIQUES

Regularization in DL

- In deep learning, regularization is a technique used to prevent **overfitting**.
- It makes slight modifications to the learning algorithm such that the model generalizes better.
- This in turn improves the model's performance on the unseen data as well.



Training Vs. Test Set Error



DL: KEY TECHNIQUES

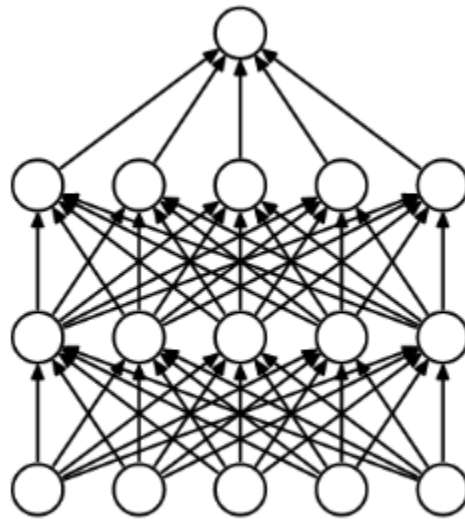
○ Regularization

❖ Different Regularization Techniques in Deep Learning

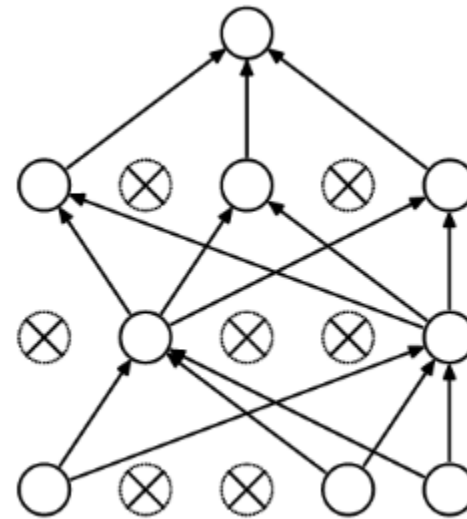
1. Dropout
2. Data augmentation
3. Early stopping
4. L2 and L1 regularization

DL: KEY TECHNIQUES

- What does dropout do in neural network?



(a) Standard Neural Net



(b) After applying dropout.

DL: KEY TECHNIQUES

❖ Data Augmentation

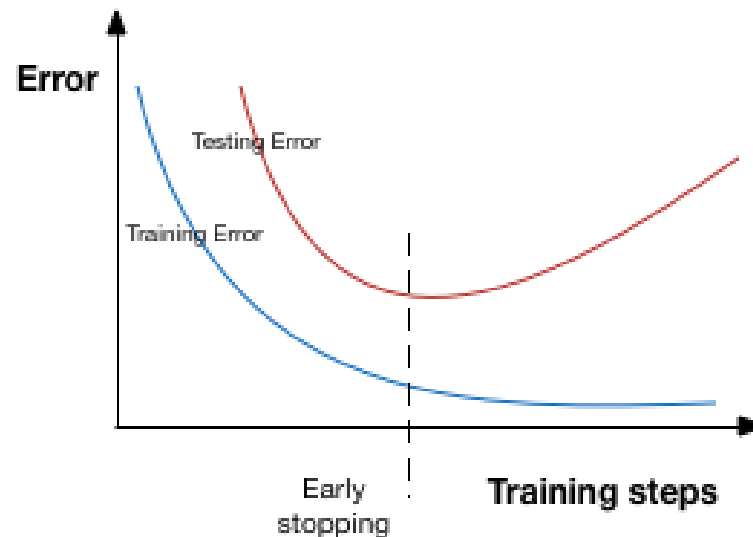
- The simplest way to reduce overfitting is to increase the size of the training data.



DL: KEY TECHNIQUES

❖ Early stopping

- In Early stopping, we keep one part of the training set as the validation set.
- When we see that the performance on the validation set is getting worse, we immediately stop the training on the model.



DL: KEY TECHNIQUES

❖ Batch normalization

- it is a technique that normalizes the input of each layer within a mini-batch during training.
- it accelerates training, makes convergence more stable, and reduces the sensitivity to weight initialization.
- It enables the use of higher learning rates and often results in better generalization.
- It is implemented as a layer within a neural network.

DL: KEY CONCEPTS

❖ Transfer learning ?

- It is a technique where a pre-trained NN is used as a starting point for a different but related task.
- Instead of training a new network from scratch, you fine-tune the pre-trained model to adapt to your specific problem by adjusting its final layers